# Development of HamSCI PSWS Ground Magnetometer and Data Visualization on the PSWS Central Website

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### Introduction

- As part of HamSCI Personal Space Weather Station (PSWS) project, magnetometers are designed to provide measurements of the geospace environment from the ground.
- Magnetometer data report magnetic field strength and direction and their temporal variations.
- PSWS Magnetometer data will be combined with high frequency (HF, 3-30 MHz) radio observations to monitor large-scale current systems and ionospheric disturbances.
- A densely-spaced magnetometer array, once established, will demonstrate their space weather monitoring capability to an unprecedented spatial extent.
- The primary goals are 1) to provide the general context of geomagnetic activity during the HF experiments; 2) to estimate ionospheric currents; 3) to measure ultra low frequency (ULF) waves; 4) to measure space weatherrelated disturbances (dB/dt).
- The magnetometer kit will be available for purchase at the TAPR store.
- Data from each location will be collected and stored in a central data archive in which users can view and download acquired data.



## HamSCI PSWS Ground Magnetometer



- PNI RM3100 magneto-inductive sensor (pnicorp.com)
- Low power, low mass, small size and large dynamic range ( $\pm 1100 \mu$ T)
- Noise: ~20 nT
- High resolution: ~on the order of 10 nT
- Tri-axial measurements
- I2C and SPI interfaces
- \$25 (sensor only)

Magnetoinductive (MI) sensing technology: uses the principle of electromagnetic induction. An inductor develops a magnetic field when a current flows through it; alternatively, a current will flow through a circuit containing an inductor when the magnetic field through it changes.

The PSWS magnetometer (MagPi) system consists of 5 basic components: a) Local computer (Raspberry Pi) (user-supplied) Local MagPi PC board

Shielded CAT5 interconnecting cable (user-supplied) Remote MagPi PC board

(e) Burial components (user-supplied, will be available for purchase at the TAPR



- MagPi samples data at a 1 Hz sample rate (per axis).
- Preliminary test shows that it measures field variations with a  $\sim$ 6 nT resolution.





The sensor module must be located away from metal objects and magnetic fields.

(a)

- Sensor burial kit installed on the ground and sensor orientation ("HEZ" system).
- For temperature stability, it is recommended that the sensor is buried under the ground.



# GUI for Data Visualization

- Magnetometer data from each location will be collected and stored in a central data archive.
- Development of a graphic user interface (GUI) is underway: Users can view and download acquired data.
- The central data archive will combine magnetometer data and radio receiver data to monitor space weather in a broader context.





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- The example data (both from the professional and HamSCI magnetometers) show ionospheric responses to magnetospheric dynamics shown in solar wind data (obtained by spacecraft).
- Data from a low-cost, magneto-inductive type magnetometer for the HamSCI PSWS project are presented and compared with a professional, science-grade magnetometer nearby.
- The HamSCI magnetometers successfully observed space weather-related phenomena, demonstrating that the its performance is very adequate for scientific investigations.
- Once established, the proposed closely-spaced magnetometer network will provide quantitative and qualitative measurements of the geospace environment from the ground for both scientific and operational purposes at a cost that will allow for crowd-sourced data contributions.

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# Example Data



• Data are background-removed. • The HamSCI magnetometer data are moving-averaged (60 sec).

### Conclusion